Important notice for March 3, 2016 Kessler Iris Data

* An experiment was conducted attempting to explore autonomous control of the yaw (rotation) angle during these flights. The specific command used is known as “condition\_yaw” which is used to define the desired heading between waypoints. In this particular case the yaw angle was set at 0 (due north). The pixhawk logged this setting as 360° or 0° and bounced between the two so when the data is plotted it shows up as bouncing between the two values. Condition\_yaw appeared useful during the flights so it may be worthwhile to try and modify the code to read in due north yaw values as 0° only.